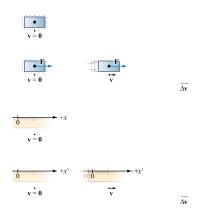
# Accelerated reference frames and fake forces (non-relativistic)

## Camera tracks inertial reference frame

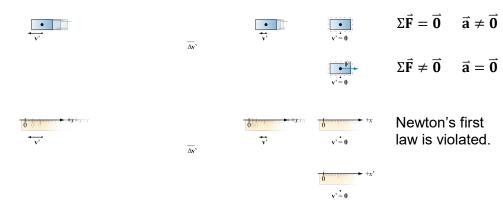


$$\Sigma \vec{\mathbf{F}} = \vec{\mathbf{0}} \qquad \vec{\mathbf{a}} = \vec{\mathbf{0}}$$

$$\Sigma \vec{F} \neq \vec{0} \qquad \vec{a} \neq \vec{0}$$

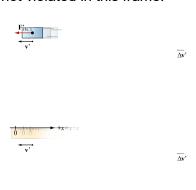


#### Camera tracks non-inertial reference frame



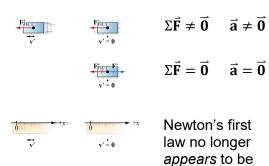
#### Tell a lie while camera tracks non-inertial reference frame

Add a fictitious force to each mass to make it seem as though Newton's first law is not violated in this frame.



Magnitude:  $F_{\text{FICT}} = ma_{\text{NON-INERTIAL}}$ Direction: Opposite acceleration of non-inertial frame relative to inertial frame

violated.



### Vocabulary

Apparent gravitational force:

$$\vec{F}_{\text{G}} + \vec{F}_{\text{FICT}} = \vec{F}_{\text{G EFFECTIVE}}$$